

Physics 566: Quantum Optics

Problem Set 6: Solutions

Problem 1: Nonclassical light via the Kerr effect

The Optical Kerr effect involves an intensity dependent index of refraction

$$\Delta n = n_2 I \quad n_2 \propto \chi^{(3)}$$

The induced polarization $P \propto \Delta n E$

\Rightarrow Interaction energy $H \propto PE^* = \Delta n I^2$

Quantizing \Rightarrow Normal order $H = \Delta n : I^2 :$
(in appropriate units)

We take the quantum Ham. It can:

$$\hat{H} = \frac{\hbar \chi^{(3)}}{2} \hat{a}^\dagger \hat{a} \hat{a}^\dagger \hat{a}$$

(a) For a strong input we can linearize

\Rightarrow Take $\hat{a} = \alpha + \hat{b}$ and keep terms only to quadratic order in \hat{b}

$$\begin{aligned} \hat{H} &= \frac{\hbar \chi^{(3)}}{2} (\alpha^\dagger + \hat{b})^2 (\alpha + \hat{b})^2 \approx \frac{\hbar \chi^{(3)}}{2} (\alpha^\dagger \alpha + \hat{b}^\dagger \hat{b} + \alpha^\dagger \hat{b} + \hat{b}^\dagger \alpha) \\ &\approx \frac{\hbar \chi^{(3)}}{2} \left[|\alpha|^4 + 2|\alpha|^2 (\hat{b}^\dagger + \alpha^\dagger \hat{b}) + 4|\alpha|^2 \hat{b}^\dagger \hat{b} + (\hat{b}^\dagger)^2 + (\alpha^\dagger)^2 \hat{b}^2 \right] \end{aligned}$$

The Hamiltonian exhibits ~~three~~ ^{four} terms

- $\frac{\hbar X^{(3)}}{2} |\alpha|^4$: Constant, classical Kerr effect

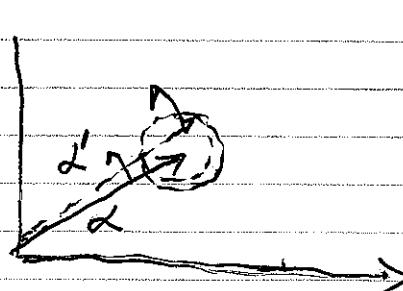
- $\hbar \chi^{(3)} |\alpha|^2 (\alpha b^\dagger + \alpha^* b)$: Phase-space displacement (parametric).

- $\frac{\partial \hbar}{\partial t} \chi^{(3)} |\alpha|^2 b^\dagger b$: Cross-phase modulation between pump and fluctuations \Rightarrow rotation in phase space

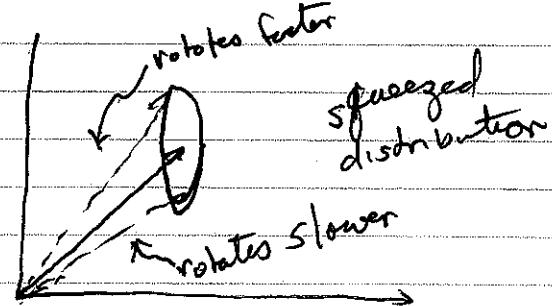
- $\frac{\hbar \chi^{(3)}}{2} |\alpha|^2 (b^{\dagger 2} e^{2i\phi} + b^2 e^{-2i\phi})$: Squeezing Hamiltonian

Thus, to this order we see that the Kerr effect will lead to squeezing. Because of the cross-phase modulation the axis of squeezing will continually rotate.

A simple classical picture explains this. Due to the Kerr effect, a phasor will rotate faster the longer the vector (bigger in density)



$t = 0$



$t > 0$

(b) The "shearing" of the uncertainty bubble eventually distorts it beyond elliptical. At this point, the linear approximation breaks down.

$$|\psi(t)\rangle = e^{-\frac{i}{\hbar} \hat{H}t} |\psi(0)\rangle$$

$$|\psi(0)\rangle = |\alpha\rangle = \sum_n c_n |n\rangle \quad c_n = \frac{\langle n | \alpha \rangle}{\sqrt{n!}}$$

$$\hat{H} = \frac{\hbar X^{(3)}}{2} \hat{a}^{\dagger 2} \hat{a}^2 = \frac{\hbar X^{(3)}}{2} [\hat{a}^{\dagger 2} \hat{a}^2 - \hat{a}^{\dagger} \hat{a}]$$

$$= \frac{\hbar X^{(3)}}{2} (\hat{n}^2 - \hat{n})$$

$$\therefore |\psi(t)\rangle = \sum_n e^{-\frac{i}{\hbar} \frac{\hbar X^{(3)} t}{2} (n^2 - n)} c_n |n\rangle$$

$$\text{when } X^{(3)}t = \pi$$

$$|\psi(t)\rangle = \sum_n e^{-i \frac{\pi}{2} (n^2 - n)} c_n |n\rangle$$

$$= e^{-\frac{(\alpha)^2}{2}} \sum_n (-i)^{n^2} \frac{(+i\alpha)^n}{\sqrt{n!}} |n\rangle$$

$$\text{Now } (-i)^{n^2} = \begin{cases} 1 & \text{even} \\ -i & \text{odd} \end{cases} = \frac{1}{\sqrt{2}} (e^{-i\pi/4} + (-1)^n e^{i\pi/4})$$

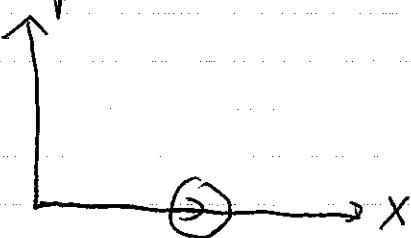
$$\Rightarrow |\psi(t)\rangle = \frac{e^{-i\pi/4}}{\sqrt{2}} e^{-\frac{(\alpha)^2}{2}} \sum_n \frac{(-i\alpha)^n}{\sqrt{n!}} |n\rangle$$

$$+ \frac{e^{i\pi/4}}{\sqrt{2}} e^{-\frac{(\alpha)^2}{2}} \sum_n \frac{(-i\alpha)^n}{\sqrt{n!}} |n\rangle$$

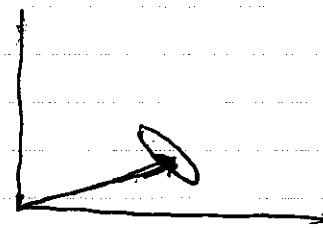
$$\Rightarrow |\Psi(t)\rangle = \frac{1}{\sqrt{2}} (e^{-i\pi/4} |i\rangle + e^{i\pi/4} |-i\rangle)$$

This is a so-called "Schrödinger cat state".

In phase space:



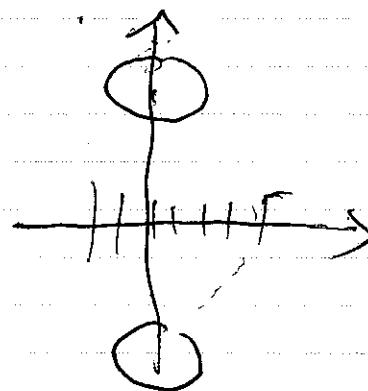
$t=0$ (take a real)



t small (squeezed)

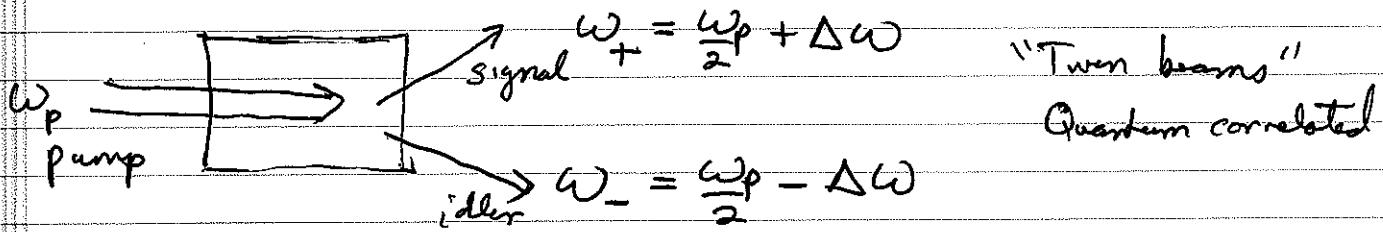


t larger
(distorted ellipse
(negative Wigner function))



Schrödinger cat !

Problem 2: Two mode squeezed states



$$\hat{H} = i\hbar G (\hat{a}_+^\dagger \hat{a}_- e^{-i\phi} - \hat{a}_+ \hat{a}_-^\dagger e^{i\phi})$$

Time evolution operator: $\hat{U}(t) = e^{-i\hat{H}t}$

$$\hat{U}(t) = e^{\xi \hat{a}_+^\dagger \hat{a}_- - \xi^* \hat{a}_+^\dagger \hat{a}_-^\dagger} = \hat{S}(\xi)$$

$$\xi = r e^{i\phi} \quad r = Gt$$

(a) Generalized Bogoliubov transformation

$$\hat{S}^\dagger(\xi) \hat{a}_\pm \hat{S}(\xi) = \hat{a}_\pm + \frac{it}{\hbar} [\hat{H}, \hat{a}_\pm] + \frac{1}{2} \left(\frac{it}{\hbar} \right)^2 [\hat{H}, [\hat{H}, \hat{a}_\pm]] + \dots$$

(Baker-Campbell-Hausdorff)

$$\text{Aside: } [\hat{H}, \hat{a}_\pm] = -i\hbar G \hat{a}_\pm^\dagger e^{-i\phi}$$

$$[\hat{H}, [\hat{H}, \hat{a}_\pm]] = -i\hbar G e^{-i\phi} [\hat{H}, \hat{a}_\pm^\dagger]$$

$$= (-i\hbar G e^{-i\phi}) (i\hbar G e^{i\phi}) \hat{a}_\pm$$

$$= -(\hbar G)^2 \hat{a}_\pm$$

etc.

$$\therefore \hat{S}^\dagger(\xi) \hat{a}_\pm \hat{S}(\xi) = \left(\sum_{n \text{ even}} \frac{r^n}{n!} \right) \hat{a}_\pm - e^{-i\phi} \left(\sum_{n \text{ odd}} \frac{r^n}{n!} \right) \hat{a}_\mp^\dagger$$

$$\Rightarrow \boxed{\hat{S}^\dagger(\xi) \hat{a}_\pm \hat{S}(\xi) = \cosh(r) \hat{a}_\pm - e^{-i\phi} \sinh(r) \hat{a}_\mp^\dagger}$$

(b) Consider quadrature operators:

$$\hat{X}_\pm \equiv \frac{\hat{a}_\pm e^{+i\theta} + \hat{a}_\mp^\dagger e^{-i\theta}}{2} \quad \text{for each mode}$$

$$\hat{S}^\dagger \hat{X}_\pm^{(\theta)} \hat{S} = (\epsilon \hat{a}_\pm - e^{-i\phi} s \hat{a}_\mp^\dagger) e^{+i\theta} + (\epsilon \hat{a}_\pm^\dagger - e^{i\phi} s \hat{a}_\mp) e^{-i\theta}$$

$$= \cancel{\epsilon} \left(\frac{\hat{a}_\pm^{+i\theta} + \hat{a}_\mp^{-i\theta}}{2} \right) - s \left(\hat{a}_\pm^{\frac{-i(\theta-\phi)}{2}} \pm \hat{a}_\mp^{\frac{i(\theta+\phi)}{2}} \right)$$

$$= \epsilon \hat{X}_\pm(\theta) - s \hat{X}_\mp(\theta - \phi) \quad (\epsilon = \cosh r) \quad (s = \sinh r)$$

Thus if we look at the fluctuations in these quadrature

$$\Delta \hat{X}_\pm^2 = \langle \hat{X}_\pm^2 \rangle - \langle \hat{X}_\pm \rangle^2$$

(where \bullet the expectation value is taken)
in squeezed vacuum

we will find no reduction below
shot noise

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$$|0_\xi\rangle \equiv S(\xi) |0_+\rangle \otimes |0_-\rangle$$

$$\Rightarrow \langle 0_\xi | \hat{X}_\pm | 0_\xi \rangle = 0$$

$$\langle 0_\xi | \hat{X}_\pm^2 | 0_\xi \rangle = \langle 0_+ | 0_- | (\zeta \hat{X}_+^{(0)} - \alpha \hat{X}_-^{(0-\phi)})^2 | 0_+\rangle \langle 0_- |$$

$$= c^2 \underbrace{\langle 0_+ 0_- | \hat{X}_\pm^{(0)} | 0_+ 0_- \rangle}_{\frac{1}{4}} + \alpha^2 \underbrace{\langle 0_+ 0_- | \hat{X}_\pm^{(0-\phi)} | 0_+ 0_- \rangle}_{\frac{1}{4}}$$

$$= \frac{1}{4} (\cosh^2(r) + \sinh^2(r)) > \frac{1}{4}$$

\Rightarrow No squeezing in single beams
(in fact extra noise in each beam)

Now consider the noise difference

$$\hat{\Delta}(0,0) \equiv \hat{X}_+(0) - \hat{X}_-(0)$$

$$\Rightarrow \hat{S}^\dagger \hat{\Delta}(0,0) \hat{S} = (\zeta \hat{X}_+(0) - \alpha \hat{X}_-(0-\phi)) - (\zeta \hat{X}_-(0) - \alpha \hat{X}_+(0-\phi))$$

$$= [\zeta \hat{X}_+(0) + \alpha \hat{X}_+(0-\phi)]$$

$$= [\zeta \hat{X}_-(0) + \alpha \hat{X}_-(0-\phi)]$$

$$\langle \Delta \hat{Y}^2(\theta, \theta') \rangle = \langle (\epsilon \hat{X}_+(\theta) + \alpha \hat{X}_+(\theta' - \phi))^2 \rangle \\ + \langle (\epsilon \hat{X}_-(\theta) + \alpha \hat{X}_-(\theta - \phi))^2 \rangle$$

Ansatz:

$$\langle (\epsilon \hat{X}_+(\theta) + \alpha \hat{X}_+(\theta' - \phi))^2 \rangle$$

$$= \epsilon^2 \langle \hat{X}_+^2(\theta) \rangle + \alpha^2 \langle \hat{X}_+^2(\theta' - \phi) \rangle$$

$$+ 2\epsilon\alpha (\langle \hat{X}_+(\theta) \hat{X}_+(\theta' - \phi) \rangle + \langle \hat{X}_+(\theta' - \phi) \hat{X}_+(\theta) \rangle)$$

$$\langle \hat{X}_+^2(\theta) \rangle = \langle \hat{X}_+^2(\theta' - \phi) \rangle = \frac{1}{4}$$

$$\langle \hat{X}_+(\theta) \hat{X}_+(\theta' - \phi) \rangle = \left\langle \left(\frac{\hat{a}_+ e^{i\theta} + \hat{a}_+^\dagger e^{-i\theta}}{2} \right) \left(\frac{\hat{a}_+ e^{i(\theta' - \phi)} + \hat{a}_+^\dagger e^{-i(\theta' - \phi)}}{2} \right) \right\rangle$$

$$= \frac{1}{4} \langle \hat{a}_+ \hat{a}_+^\dagger \rangle e^{i(\theta - \theta' - \phi)}$$

$$= \underbrace{\epsilon^2 + \alpha^2 + 2\epsilon\alpha \cos(\theta - \theta' - \phi)}_{4}$$

$$= \frac{1}{4} \left[e^{-2r} \sin^2 \left(\frac{\theta - \theta' - \phi}{2} \right) + e^{2r} \cos^2 \left(\frac{\theta - \theta' - \phi}{2} \right) \right]$$

$$\therefore \boxed{\langle \Delta \hat{Y}^2(\theta, \theta') \rangle = \frac{1}{2} \left[e^{-2r} \sin^2 \left(\frac{\theta - \theta' - \phi}{2} \right) \right.}$$

$$\left. + e^{2r} \cos^2 \left(\frac{\theta - \theta' - \phi}{2} \right) \right]$$

Interpretation:

When $\theta - \theta - \phi = \pi$, the modes are maximally correlated \Rightarrow Squeezing

(c) Number correlations in twin beams:

$$\hat{S}_{\pm}(r)|0_+\rangle\langle 0_-| = e^{r(\hat{a}_+^\dagger\hat{a}_-^\dagger - \hat{a}_+\hat{a}_-)} |0_+\rangle\langle 0_-|$$

take ξ real

To apply this operator, we need the disentangling theorem (see Walls & Milburn, eq. (5.63))

$$\hat{S}_{\pm}(r) = e^{\Gamma\hat{a}_+^\dagger\hat{a}_-^\dagger} e^{-g(\hat{a}_+^\dagger\hat{a}_+ + \hat{a}_-^\dagger\hat{a}_- + 1)} e^{-\Gamma\hat{a}_+\hat{a}_-}$$

$$\text{where } \Gamma = \tanh(r) \quad g = \ln(\cosh r)$$

Applying this to the vacuum

$$\begin{aligned} \hat{S}_{\pm}(r)|0_+\rangle\langle 0_-| &= e^{\Gamma\hat{a}_+^\dagger\hat{a}_-^\dagger} e^{-g}|0_+\rangle\langle 0_-| \\ &= \frac{1}{e^g} \sum_{n=0}^{\infty} \Gamma^n \frac{(\hat{a}_+^\dagger)^n}{\sqrt{n!}} \frac{(\hat{a}_-^\dagger)^n}{\sqrt{n!}} |0_+\rangle\langle 0_-| \end{aligned}$$

$$\rightarrow \boxed{\hat{S}_{\pm}(r)|0_+\rangle\langle 0_-| = \frac{1}{\cosh(r)} \sum_n [\tanh(r)]^n |n_+\rangle\langle n_-|}$$

Note for r small, we get the correlated photon pair (plus vacuum)

d)

To obtain the margin density operator we trace over one of the degrees of freedom, e.g.,

$$\hat{\rho}_+ = \text{Tr}_- (\hat{1} \Psi_{+-} \langle \Psi_{+-} |) \\ = \frac{1}{\cosh^2(r)} \sum_n [\tanh^2(r)]^n |n\rangle_+ \langle n|$$

This has the form of a thermal state

$$\hat{\rho}_{\text{thermal}} = \sum_{n=0}^{\infty} P_n |n\rangle \langle n|$$

where $P_n = \frac{(e^{-\beta \hbar \omega})^n}{Z} = \frac{n^n}{(1+n)^{n+1}}$ is the Bose-Einstein distribution

Setting $\left(\frac{n}{1+n}\right)^n \frac{1}{1+n} = \frac{(\tanh^2(r))^n}{\cosh^2(r)}$

Using $\sinh^2(r) - \cosh^2(r) = 1$

$$\tanh^2(r) = 1 = \frac{1}{\cosh^2(r)}$$

$$\Rightarrow \boxed{n = \sinh^2(r)}$$

(e) Wigner function of the two mode squeezed state

For two modes

$$W(\alpha_+, \alpha_-) = \frac{1}{\pi^4} \int d\beta_+^2 \int d\beta_-^2 \chi(\beta_+, \beta_-) e^{\alpha_+ \beta_+^* - \alpha_+^* \beta_+} \\ \times e^{\alpha_- \beta_-^* - \alpha_-^* \beta_-}$$

where the characteristic function is

$$\chi(\beta_+, \beta_-) = \text{Tr} (\hat{D}_+(\beta_+) \hat{D}_-(\beta_-))$$

$$= \langle 0_r | \hat{D}_+(\beta_+) \hat{D}_-(\beta_-) | 0_r \rangle$$

$$| 0_r \rangle = \exp \{ r (\hat{a}_+ \hat{a}_- - \hat{a}_+^\dagger \hat{a}_-^\dagger) \} | 0_+ \rangle \otimes | 0_- \rangle$$

$$\Rightarrow \chi(\beta_+, \beta_-) = \langle 0_r | e^{\beta_+ \hat{a}_+^\dagger - \beta_+^* \hat{a}_+} e^{\beta_- \hat{a}_-^\dagger - \beta_-^* \hat{a}_-} | 0_r \rangle$$

$$= \langle 0_r | e^{(c\beta_+ - \alpha\beta_+^*) \hat{a}_+^\dagger - (c\beta_+^* - \alpha\beta_+) \hat{a}_+} \\ e^{(c\beta_- - \alpha\beta_-^*) \hat{a}_-^\dagger - (c\beta_-^* - \alpha\beta_-) \hat{a}_-} | 0_r \rangle$$

$$= \langle 0_+ | \hat{D}_+(c\beta_+ - \alpha\beta_+^*) | 0_+ \rangle \langle 0_- | \hat{D}_-(c\beta_- - \alpha\beta_-^*) | 0_- \rangle$$

$$= e^{-\frac{1}{2}|c\beta_+ - \alpha\beta_+^*|^2} e^{-\frac{1}{2}|c\beta_- - \alpha\beta_-^*|^2}$$

Fourier transforming, using our Gaussian integral from PS#8

$$W(\alpha_+, \alpha_-) = \frac{4}{\pi^2} \exp \left[-2 |\alpha_+ \cosh r - \alpha_-^* \sinh r|^2 \right. \\ \left. - 2 |\alpha_- \cosh r - \alpha_+^* \sinh r|^2 \right]$$

In terms of the quadrature $x_{\pm} + i p_{\pm} \equiv \alpha_{\pm}$

$$W(x_{\pm}, p_{\pm}) = \frac{4}{\pi^2} \exp \left[-2(x_+ c - x_- s)^2 - 2(p_+ e + p_- s)^2 - 2(x_- c - x_+ s)^2 - 2(p_- e + p_+ s)^2 \right]$$

$$= \frac{4}{\pi^2} \exp \left[-2(x_+^2 + x_-^2 + p_+^2 + p_-^2)(e^2 + s^2) + 8(x_+ x_- - p_+ p_-) cs \right]$$

with $e^2 + s^2 = \frac{e^{2r} + e^{-2r}}{2}$ $cs = \frac{e^{2r} - e^{-2r}}{4}$

$$\Rightarrow W(x_{\pm}, p_{\pm}) = \frac{4}{\pi^2} \exp \left[-e^{+2r} (x_+^2 + x_-^2 - 2x_+ x_- + p_+^2 + p_-^2 + 2p_+ p_-) - e^{-2r} (x_+^2 + x_-^2 + 2x_+ x_- + p_+^2 + p_-^2 - 2p_+ p_-) \right]$$

$$\Rightarrow W(x_{\pm}, p_{\pm}) = \frac{4}{\pi^2} \exp \left[-e^{+2r} \{(x_+ - x_-)^2 + (p_+ + p_-)^2\} - e^{-2r} \{(x_+ + x_-)^2 + (p_+ - p_-)^2\} \right]$$

In the limit $r \rightarrow \infty$ the squeezed direction goes to zero and the stretched direction to ∞ , yielding a delta function

$$W(x_{\pm}, p_{\pm}) \rightarrow C \delta(x_+ + x_-) \delta(p_+ - p_-)$$

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Problem 3: Gaussian States in Quantum Optics

We consider the states associated with n modes of the quantized electromagnetic field. They are described by n -pairs of quadratures ordered as

$$\vec{z} = (x_1, p_1, x_2, p_2, \dots, x_n, p_n)$$

The operators satisfy the canonical commutation relations

$$[\hat{z}_i, \hat{z}_j] = \frac{i}{2} \sum_{ij}$$

where $\sum = \begin{bmatrix} 0 & 1 & & \\ -1 & 0 & & \\ & & \ddots & \\ & & & 0 & 1 \\ & & & -1 & 0 \end{bmatrix}$

(a) For a given mode, we defined the phase-space displacement operator

$$\hat{D}(\alpha) = e^{\alpha \hat{a}^\dagger - \alpha^* \hat{a}} = e^{-2i(X\hat{P} - P\hat{X})}$$

where $\alpha = X + iP$ $\hat{q} = \hat{X} + i\hat{P}$

Note: $(X \ P) \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} \hat{X} \\ \hat{P} \end{bmatrix} = X\hat{P} - P\hat{X} = (\vec{z} | z)$

$\Rightarrow \hat{D}(\alpha) = e^{-2i(\vec{z} | z)}$

More generally, for multi-mode $\hat{D}(\vec{z}) = \prod_k \hat{D}_k(\alpha_k)$

The characteristic function for a general Gaussian state has the form:

$$\chi(\vec{z}) \equiv \text{Tr}(\hat{\rho} \hat{D}(\vec{z})) = e^{-2(\vec{z}|C|\vec{z}) + 2i(\vec{d}^\dagger \vec{z})}$$

where $(\vec{z}|C|\vec{z}) = z_i \sum_{ij} C_{jk} \sum_{kl} z_k z_l$ (sum over repeated indices)

$$(\vec{d}^\dagger \vec{z}) = d_i \sum_{ij} z_j$$

For clarity, consider one mode first and let $\vec{d} = (x_0, p_0)$

$$C = \begin{bmatrix} C_{xx} & C_{xp} \\ C_{px} & C_{pp} \end{bmatrix}$$

$$\Rightarrow \chi(x, p) = \exp \left\{ -2(p^2 C_{xx} + x^2 C_{pp} - xp(C_{xp} + C_{px})) \right\} e^{2i(x_0 p - p_0 x)}$$

$$\Rightarrow \frac{\partial}{\partial x} \chi(x, p) = (-4p C_{xx} + 2x(C_{xp} + C_{px}) - 2i p_0) \chi(x, p)$$

$$\frac{\partial}{\partial p} \chi(x, p) = (-4x C_{pp} + 2p(C_{xp} + C_{px}) + 2i x_0) \chi(x, p)$$

$$\Rightarrow \frac{\partial}{\partial x} \chi(\vec{z}) \Big|_{\vec{z}=0} = -2i p_0$$

$$\frac{\partial}{\partial p} \chi(\vec{z}) \Big|_{\vec{z}=0} = 2i x_0$$

$$\begin{aligned}
 \text{Now, } \frac{\partial}{\partial X} \chi(\vec{z}) \Big|_{\vec{z}=0} &= \frac{\partial}{\partial X} \text{Tr}(\hat{p} e^{-2i(X\hat{P} - P\hat{X})}) \Big|_{\vec{z}=0} \\
 &= -2i \text{Tr}(\hat{p} \hat{P}) = -2i \langle \hat{p} \rangle \\
 \frac{\partial}{\partial P} \chi(\vec{z}) \Big|_{\vec{z}=0} &= \frac{\partial}{\partial P} \text{Tr}(\hat{p} e^{-2i(X\hat{P} - P\hat{X})}) \Big|_{\vec{z}=0} \\
 &= 2i \text{Tr}(\hat{p} \hat{X}) = 2i \langle \hat{X} \rangle
 \end{aligned}$$

$$\Rightarrow \langle \hat{X} \rangle = X_0 \quad \langle \hat{p} \rangle = P_0$$

or $\langle \hat{z} \rangle = \vec{d}$

For the second derivatives we see

$$\frac{\partial^2}{\partial X^2} \chi(X, P) \Big|_{\vec{z}=0} = -4C_{PP} - 4P_0^2$$

$$\frac{\partial^2}{\partial P^2} \chi(X, P) \Big|_{\vec{z}=0} = -4C_{XX} - 4X_0^2$$

$$\frac{\partial^2}{\partial X \partial P} \chi(X, P) \Big|_{\vec{z}=0} = 2(C_{XP} + C_{PX}) + 4X_0 P_0$$

$$\text{And: } \frac{\partial^2}{\partial X^2} \chi(X, P) \Big|_{\vec{z}=0} = \frac{\partial^2}{\partial X^2} \text{Tr}(\hat{p} D(\vec{z})) \Big|_{\vec{z}=0} = -4 \langle \hat{p}^2 \rangle$$

$$\frac{\partial^2}{\partial P^2} \chi(X, P) \Big|_{\vec{z}=0} = \frac{\partial^2}{\partial P^2} \text{Tr}(\hat{p} D(\vec{z})) \Big|_{\vec{z}=0} = -4 \langle \hat{X}^2 \rangle$$

$$\frac{\partial^2}{\partial X \partial P} \chi(X, P) \Big|_{\vec{z}=0} = \frac{\partial^2}{\partial X \partial P} \text{Tr}(\hat{p} D(\vec{z})) \Big|_{\vec{z}=0} = 2 \langle X \hat{P} + P \hat{X} \rangle$$

Thus we see:

$$C_{pp} = \langle \hat{p}^2 \rangle - \langle \hat{p} \rangle^2$$

$$C_{xx} = \langle \hat{x}^2 \rangle - \langle \hat{x} \rangle^2$$

$$C_{xp} = C_{px} = \frac{\langle \hat{x}\hat{p} + \hat{p}\hat{x} \rangle}{2} - \langle \hat{x} \rangle \langle \hat{p} \rangle$$

Or generally $C_{ij} = \frac{1}{2} \langle (\hat{z}_i - \langle \hat{z}_i \rangle)(\hat{z}_j - \langle \hat{z}_j \rangle) \rangle$

Covariance matrix

this generalizes for multi-modes if we just keep track of all the indeces.

(c) The Wigner function is the Fourier transform of the characteristic function.

$$W(\vec{z}) = \int \frac{d\vec{z}'}{\pi^n} \chi(\vec{z}') e^{2i(\vec{z}'|\vec{z})}$$

Again, let us consider this for one mode

$$W(x, p) = \int \frac{dx' dp'}{\pi} \chi(x', p') e^{2i(xp' - x'p)}$$

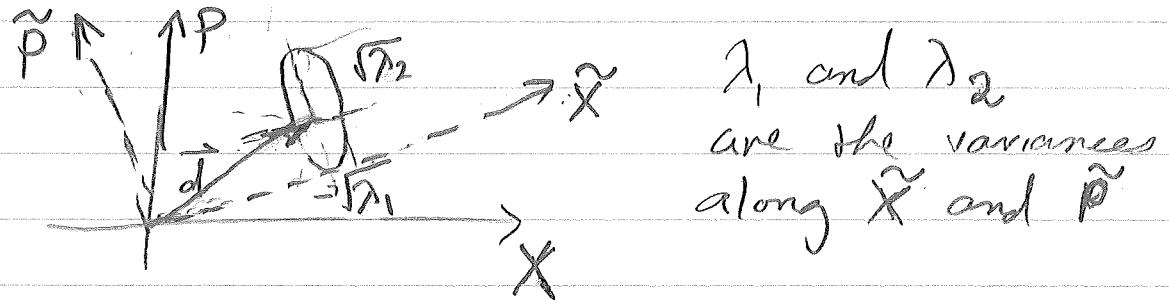
The Fourier transform of a Gaussian is a Gaussian. In 1D

$$f(x) = A e^{-\frac{(x-x_0)^2}{2\sigma^2}} \Rightarrow \tilde{f}(k) = A \sqrt{\frac{2\pi}{\sigma}} e^{-\frac{\sigma^2 k^2}{2}} e^{ikx_0}$$

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What we have is a multi-variable Gaussian. The key is that if we diagonalize the covariance matrix then the multivariate Gaussian factorizes, and we have a product of 1D Gaussians.

For example, for one mode, let λ_1 and λ_2 by the eigenvalues of the covariance matrix, and \tilde{X}, \tilde{P} be the eigen-quadratures



⇒ If the Characteristic function is

$$\chi(\tilde{X}, \tilde{P}) = e^{-2(\lambda_1 \tilde{X}^2 + i\tilde{d}_X \tilde{X})} e^{-2(\lambda_2 \tilde{P}^2 - i\tilde{d}_P \tilde{P})}$$

The Wigner function is

$$W(\tilde{X}, \tilde{P}) = \frac{2\pi}{\sqrt{\lambda_1 \lambda_2}} e^{-\frac{(\tilde{X}-d_X)^2}{2\lambda_1}} e^{-\frac{(\tilde{P}-d_P)^2}{2\lambda_2}}$$

Note in the eigenbasis, the covariance matrix

$$C = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \Rightarrow C^{-1} = \begin{bmatrix} \frac{1}{\lambda_1} & 0 \\ 0 & \frac{1}{\lambda_2} \end{bmatrix}$$

For an arbitrary number of modes, this generalizes to

$$W(\vec{z}) = \frac{(2\pi)^n}{\sqrt{\lambda_1 \lambda_2 \dots \lambda_{2n}}} \prod_{i=1}^n e^{-\frac{(\tilde{x}_i - d_{x_i})^2}{2\lambda_{1i}}} e^{-\frac{(\tilde{p}_i - d_{p_i})^2}{2\lambda_{2i}}}$$

Note: $\prod_i \lambda_i = \det(C) = \text{determinant of covariance matrix}$

If $\mathcal{D} = 0$ we can also compactly write the Wigner function in terms of the original quadratures

$$W(\vec{z}) = \frac{(2\pi)^n}{\sqrt{\det C}} e^{-\frac{1}{2} (\vec{z} | C^{-1} | \vec{z})}$$

↑ inverse of covariance matrix

(d) We consider the unitary transformations that perform a symplectic map

$$\hat{U}^\dagger \vec{z}_i \hat{U} = S_{ij} \hat{z}_j \quad (\text{sum over } j)$$

We want to show how the covariance matrix of a state transforms.

Given a state $\hat{\rho}$, $\chi(\vec{z}) = \text{Tr}(\hat{\rho} \hat{D}(\vec{z}))$

The characteristic function of a transformed state

$$\begin{aligned} \text{is } \chi'(\vec{z}) &= \text{Tr}(\hat{U} \hat{\rho} \hat{U}^\dagger \hat{D}(\vec{z})) = \text{Tr}(\hat{\rho} \hat{U} \hat{U}^\dagger \hat{D}(\vec{z}) \hat{U}) \\ &\quad \text{Tr}(\hat{\rho} \hat{U} \exp\{-\alpha_i z_i \Sigma_{ij} \hat{z}_j\} \hat{U}^\dagger) \end{aligned}$$

$$\Rightarrow \chi'(\vec{z}) = \text{Tr}(\rho \exp \{-2i z_i \Sigma_{ij} \vec{z}_j \vec{z}^T\})$$

$$= \text{Tr}(\rho \exp \{-2i z_i \Sigma_{ij} S^{-1}_{jk} \vec{z}_k \vec{z}\})$$

Aside: $S^{-1} = \Sigma^{-1} S^T \Sigma$

(Property of symplectic matrices)

$$\text{Thus } \chi'(\vec{z}) = \text{Tr}(\rho \exp \{-2i z_i \Sigma_{ij} S^T_{jk} \Sigma_{kl} \vec{z}_k\})$$

$$= \text{Tr}(\rho \exp \{-2i (S \vec{z})^T \vec{z}\})$$

$$\Rightarrow \boxed{\chi'(\vec{z}) = \chi(S \vec{z})}$$

The new characteristic function is obtained by transforming the $\vec{z} \Rightarrow S \vec{z}$

For Gaussian State: $\chi(\vec{z}) = e^{-2 \sum_i z_i \Sigma_{ij} G_k \Sigma_{kl} z_l}$

Upon a symplectic transformation

$$\chi'(\vec{z}) = \chi(S \vec{z}) = e^{-2 \sum_i S_{ik} z_k \sum_{ij} \Sigma_{ij} G_k \Sigma_{kl} S_{lm} z_m}$$

$$= e^{-2 \sum_k S_{ki}^T \Sigma_{ij} C_{jk} \Sigma_{kl} S_{lm} z_m}$$

Aside: For symplectic matrices $S^T \Sigma = \Sigma S$

$$\Rightarrow \chi'(\vec{z}) = e^{-2 \sum_i \Sigma_{ij} (S_{ik} C_{kj} S_{lm}^T) \sum_{mn} z_m z_n}$$

(Next Page)

Thus, under a symplectic transformation,
the covariance matrix of the Gaussian
transforms as:

$$C \Rightarrow S C S^T$$

(e) Now we consider simple transformations

- Linear optics: $\hat{U} = e^{-i\theta_{ij}} \hat{a}_i \hat{a}_j^*$
R Hermitian matrix

$$\hat{J} = \prod_a e^{-i\theta_a} \hat{a}_a^* \hat{a}_a$$
 new modes

where θ_a are eigenvalues of θ_{ij}

$$\Rightarrow \hat{J}^* \hat{a}_a \hat{J} = e^{-i\theta_a} \hat{a}_a$$

or $\begin{cases} \hat{X}_d = \cos\theta_d \hat{X}_d + \sin\theta_d \hat{P}_d \\ \hat{P}_d = \cos\theta_d \hat{P}_d - \sin\theta_d \hat{X}_d \end{cases}$

↔ Symplectic transformation

- Squeezing $\hat{U} = \exp(\sum_j^* \hat{a}_j \hat{a}_j^* - \sum_i \hat{a}_i \hat{a}_i^*)$

$$\hat{U} \hat{a}_i \hat{U}^* = \cosh(r_i) \hat{a}_i - e^{2i\phi_i} \sinh(r_i) \hat{a}_i^*$$

where $r_i = r_i e^{i2\phi_i}$

⇒ Squeezing and anti-squeezing
along some quadratures

This is a symplectic transformation as it is linear in \hat{q} and \hat{q}^\dagger and preserves the commutation relation

(f) The symplectic transformations are the linear transformations on the quadratures

- For the case of linear optics, the matrix S_{ij} an orthogonal matrix)
- $$S^T S = 1,$$

Since it corresponds to general rotation in the multidimensional phase space

- For the case of squeezing

The general symplectic matrix can be decomposed in so-called "Euler form"

$$S = \Theta_1 \left(\bigoplus_{j=1}^n \begin{bmatrix} e^{r_j} & 0 \\ 0 & e^{-r_j} \end{bmatrix} \right) \Theta_2$$

The matrices Θ_1 and Θ_2 are orthogonal rotations of the type arising in linear optics. The matrix

$$\left(\bigoplus_{j=1}^n \begin{bmatrix} e^{r_j} & 0 \\ 0 & e^{-r_j} \end{bmatrix} \right)$$

performs squeezing along X, P quadratures

Stated in another way:

$$S = \Theta_3 \Theta_2^T \left(\oplus \begin{bmatrix} e^{r_i} & 0 \\ 0 & e^{-r_i} \end{bmatrix} \right) \Theta_2$$

Similarity transformation

Here, I have written $\Theta_i = \Theta_3 \Theta_2^T$

Geometrically, this corresponds to rotating the principle axes of the ellipse to X-P, applying squeezing, and then a final rotation

(f)-For linear optics the effect on the covariance matrix is a pure rotation

$$C \Rightarrow \Theta^T C \Theta$$

where $\Theta = \bigoplus_{\alpha} \begin{bmatrix} \cos \theta_{\alpha} & -\sin \theta_{\alpha} \\ \sin \theta_{\alpha} & \cos \theta_{\alpha} \end{bmatrix}$

where θ_{α} are the eigenvalues of Θ_{ij}

This gives the expected results of just causing a rotation in phase space without affecting the fluctuations in any quadrature.

-For squeezing

$$C \Rightarrow O_1 D O_2 C O_2^T D O_1^T$$

where $D = \oplus \begin{bmatrix} e^{2r} & 0 \\ 0 & e^{-2r} \end{bmatrix}$

Here O_2 rotates the quadratures to be squeezed along the x-p axis, D performs the squeezing, and O_1 rotates the final ellipse into place, as expected.

(g) Consider a single mode to start
(this easily generalizes for multi-mode case)

Input covariance matrix for vacuum

$$C = \frac{1}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$C \Rightarrow O_1 D^2 O_1^T = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} e^{+2r} & 0 \\ 0 & e^{-2r} \end{bmatrix} \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$$

$$= \begin{bmatrix} e^{2r} \cos^2\theta + e^{-2r} \sin^2\theta & \sinh(2r) \sin 2\theta \\ \sinh(2r) \sin 2\theta & e^{-2r} \cos^2\theta + e^{2r} \sin^2\theta \end{bmatrix}$$